

Neurocontrol Learning Control Systems Inspired By

Modelling, Simulation and Control of Non-linear Dynamical Systems Patricia Melin, Oscar Castillo. 2001-10-25 These authors use soft computing techniques and fractal theory in this new approach to mathematical modeling, simulation and control of complex non-linear dynamical systems. First, a new fuzzy-fractal approach to automated mathematical modeling of non-linear dynamical systems is presented. It is illustrated with examples on the PROLOG programming language.

Introduction to Mobile Robot Control Spyros G Tzafestas. 2013-10-03 Introduction to Mobile Robot Control provides a complete and concise study of modeling, control, and navigation methods for wheeled non-holonomic and omnidirectional mobile robots and manipulators. The book begins with a study of mobile robot drives and corresponding kinematic and dynamic models, and discusses the sensors used in mobile robotics. It then examines a variety of model-based, model-free, and vision-based controllers with unified proof of their stabilization and tracking performance, also addressing the problems of path, motion, and task planning, along with localization and mapping topics. The book provides a host of experimental results, a conceptual overview of systemic and software mobile robot control architectures, and a tour of the use of wheeled mobile robots and manipulators in industry and society. Introduction to Mobile Robot Control is an essential reference, and is also a textbook suitable as a supplement for many university robotics courses. It is accessible to all and can be used as a reference for professionals and researchers in the mobile robotics field. Clearly and authoritatively presents mobile robot concepts Richly illustrated throughout with figures and examples Key concepts demonstrated with a host of experimental and simulation examples No prior knowledge of the subject is required; each chapter commences with an introduction and background

The Industrial Electronics Handbook - Five Volume Set Bogdan M. Wilamowski, J. David Irwin. 2011-03-04 Industrial electronics systems govern so many different functions that vary in complexity—from the operation of relatively simple applications, such as electric motors, to that of more complicated machines and systems, including robots and entire fabrication processes. The Industrial Electronics Handbook, Second Edition combines traditional and new

Introduction to Artificial Neural Networks Sivanandam S., Paulraj M. 2009-11-01 This fundamental book on Artificial Neural Networks has its emphasis on clear concepts, ease of understanding and simple examples. Written for undergraduate students, the book presents a large variety of standard neural networks with architecture, algorithms and applications.

Soft Computing and Intelligent Systems Madan M. Gupta. 1999-10-28 The field of soft computing is emerging from the cutting edge research over the last ten years devoted to fuzzy engineering and genetic algorithms. The subject is being called soft computing and computational intelligence. With acceptance of the research fundamentals in these important areas, the field is expanding into direct applications through engineering and systems science. This book covers the fundamentals of this emerging field, as well as direct applications and case studies. There is a need for practicing engineers, computer scientists, and system scientists to directly apply fuzzy engineering into a wide array of devices and systems.

Inversion Method in the Discrete-time Nonlinear Control Systems Synthesis Problems Ülle Kotta. 2006-01-21 The purpose of this book is twofold: To survey control system design methods based on the system inversion technique and to collect into one place the many recent results in the field. It has been known for some time that inverse systems may be used to solve numerous control problems. Despite the importance and conceptual simplicity of this topic there appears to be no monograph written on it. The purpose of this work is therefore to present and apply a systematic design method which bases itself on the fundamental system property of invertibility. Many different theoretical and practical aspects are considered in this volume working from elementary topics in the first section to current research in the second.

MICAI 2000: Advances in Artificial Intelligence Osvaldo Cairo, Enrique L. Sucar, Francisco J. Cantu. 2006-12-30 Fifty years ago, A. Turing predicted that by 2000 we would have a machine that could pass the Turing test. Although this may not yet be true, AI has advanced significantly in these 50 years, and at the dawn of the XXI century is still an active and challenging field. This year is also significant for AI in Mexico, with the merging of the two major AI conferences into the biennial Mexican International Conference on Artificial Intelligence (MICAI) series. MICAI is the union of the Mexican National AI Conference (RNIA) and the International AI Symposium (ISAI), organized annually by the Mexican Society for AI (SMIA, since 1984) and by the Monterrey Institute of Technology (ITESM, since 1988), respectively. The first Mexican International Conference on Artificial Intelligence, MICAI 2000, took place April 11-14, 2000, in the city of Acapulco, Mexico. This conference seeks to promote research in AI, and cooperation among Mexican researchers and their peers worldwide. We welcome you all. Over 163 papers from 17 different countries were submitted for consideration to MICAI 2000. After reviewing them thoroughly, MICAI's program committee, referees, and program chair accepted 60 papers for the international track. This volume contains the written version of the papers and invited talks presented at MICAI. We would like to acknowledge the support of the American Association for Artificial Intelligence (AAAI), and the International Joint Conference on Artificial Intelligence (IJCAI). We are specially grateful for the warm hospitality and generosity offered by the Acapulco Institute of Technology.

Analysis and Synthesis of Fuzzy Control Systems Gang Feng. 2018-09-03 Fuzzy logic control (FLC) has proven to be a popular control methodology for many complex systems in industry, and is often used with great success as an alternative to conventional control techniques. However, because it is fundamentally model free, conventional FLC suffers from a lack of tools for systematic stability analysis and controller design. To address this problem, many model-based fuzzy control approaches have been developed, with the fuzzy dynamic model or the Takagi and Sugeno (T-S) fuzzy model-based approaches receiving the greatest attention. Analysis and Synthesis of Fuzzy Control Systems: A Model-Based Approach offers a unique reference devoted to the systematic analysis and synthesis of model-based fuzzy control systems. After giving a brief review of the varieties of FLC, including the T-S fuzzy model-based control, it fully explains the fundamental concepts of fuzzy sets, fuzzy logic, and fuzzy systems. This enables the book to be self-contained and provides a basis for later chapters, which cover: T-S fuzzy modeling and identification via nonlinear models or data Stability analysis of T-S fuzzy systems Stabilization controller synthesis as well as robust H_∞ and observer and output feedback controller synthesis Robust controller synthesis of uncertain T-S fuzzy systems Time-delay T-S fuzzy systems Fuzzy model predictive control Robust fuzzy filtering Adaptive control of T-S fuzzy systems A reference for scientists and engineers in systems and control, the book also serves the needs of graduate students exploring fuzzy logic control. It readily demonstrates that conventional control technology and fuzzy logic control can be elegantly combined and further developed so that disadvantages of conventional FLC can be avoided and the horizon of conventional control technology greatly extended. Many chapters feature application simulation examples and practical numerical examples based on MATLAB®.

The Modeling of Uncertainty in Control Systems Roy S. Smith. 1994 This book is a collection of work arising from a NSF/ AFOSR sponsored workshop held at the University of California, Santa Barbara, 18-20th June 1992. Sixty-nine researchers, from nine countries, participated. Twelve keynote essays give an overview of the field and speculate on future directions and nineteen technical papers delineate the state of the art in the field. This book serves both as an introduction to the topic and as a reference on the current technical problems and approaches.

Foundations of Computer Science Wilfried Brauer. 1997-10-24 Content Description #Dedicated to Wilfried Brauer. #Includes bibliographical references and index.

Adaptive Modelling, Estimation and Fusion from Data Chris Harris, Xia Hong, Qiang Gan. 2012-10-05 This book brings together for the first time the complete theory of data based neurofuzzy modelling and the linguistic attributes of fuzzy logic in a single cohesive mathematical framework. After introducing the basic theory of data based modelling new concepts including extended additive and multiplicative submodels are developed.

All of these algorithms are illustrated with benchmark examples to demonstrate their efficiency. The book aims at researchers and advanced professionals in time series modelling, empirical data modelling, knowledge discovery, data mining and data fusion.

Neurocontrol H. Tolle, E. Ersü. 1992-03-05 Since heavily non-linear and/or very complex processes still pose a problem for automatic control, they can often be handled easily by human operators. The book describes results from ten years of research on learning control loops, which imitate these abilities. After discussing the difference between adaptive control and some background on human information processing and behaviour is put forward and some learning control loop structure related to these ideas is shown. The ability to learn is due to memories, which are able to interpolate for multi-dimensional input spaces between scattered output values. A neuronally and mathematically inspired memory layout are compared and it is shown that they learn much faster than backpropagation neural networks, which can also be used. For the learning control loop different architectures are given. Their usefulness is demonstrated by simulation and results from applications to real pilot plants. The book should be of interest for control engineers as well as researchers in neural net applications and/or artificial intelligence. The usual mathematical background of engineers is sufficient.

Neural Adaptive Control Technology Rafal Zbikowski, Kenneth J Hunt. 1996-04-13 This book is an outgrowth of the workshop on Neural Adaptive Control Technology, NACT I, held in 1995 in Glasgow. Selected workshop participants were asked to substantially expand and revise their contributions to make them into full papers. The workshop was organised in connection with a three-year European Union funded Basic Research Project in the ESPRIT framework, called NACT, a collaboration between Daimler-Benz (Germany) and the University of Glasgow (Scotland). A major aim of the NACT project is to develop a systematic engineering procedure for designing neural controllers for nonlinear dynamic systems. The techniques developed are being evaluated on concrete industrial problems from Daimler-Benz. In the book emphasis is put on development of sound theory of neural adaptive control for nonlinear control systems, but firmly anchored in the engineering context of industrial practice. Therefore the contributors are both renowned academics and practitioners from major industrial users of neurocontrol.

Encyclopedia of Computer Science and Technology Allen Kent, James G. Williams. 1997-02-14 Artificial Intelligence in Economics and Management to Requirements Engineering

Intelligent Systems Bogdan M. Wilamowski, J. David Irwin. 2018-10-03 The Industrial Electronics Handbook, Second Edition combines traditional and newer, more specialized knowledge that will help industrial electronics engineers develop practical solutions for the design and implementation of high-power applications. Embracing the broad technological scope of the field, this collection explores fundamental areas, including analog and digital circuits, electronics, electromagnetic machines, signal processing, and industrial control and communications systems. It also facilitates the use of intelligent systems—such as neural networks, fuzzy systems, and evolutionary methods—in terms of a hierarchical structure that makes factory control and supervision more efficient by addressing the needs of all production components. Enhancing its value, this fully updated collection presents research and global trends as published in the IEEE Transactions on Industrial Electronics Journal, one of the largest and most respected publications in the field. As intelligent systems continue to replace and sometimes outperform human intelligence in decision-making processes, they have made substantial contributions to the solution of very complex problems. As a result, the field of computational intelligence has branched out in several directions. For instance, artificial neural networks can learn how to classify patterns, such as images or sequences of events, and effectively model complex nonlinear systems. Simple and easy to implement, fuzzy systems can be applied to successful modeling and system control. Illustrating how these and other tools help engineers model nonlinear system behavior, determine and evaluate system parameters, and ensure overall system control, Intelligent Systems: Addresses various aspects of neural networks and fuzzy systems Focuses on system optimization, covering new techniques such as evolutionary methods, swarm, and ant colony optimizations Discusses several applications that deal with methods of computational intelligence Other volumes in the set: Fundamentals of Industrial Electronics Power Electronics and Motor Drives Control and Mechatronics Industrial Communication Systems

Neuro-Control and its Applications Sigeru Omatu, Marzuki B. Khalid, Rubiyah Yusof. 2012-12-06 The series Advances in Industrial Control aims to report and encourage technology transfer in control engineering. The rapid development of control technology impacts all areas of the control discipline. New theory, new controllers, actuators, sensors, new industrial processes, computer methods, new applications, new philosophies, , new challenges. Much of this development work resides in industrial reports, feasibility study papers and the reports of advance collaborative projects. The series offers an opportunity for researchers to present an extended exposition of such new work in all aspects of industrial control for wider and rapid dissemination. Sigeru Omatu, Marzuki Khalid, and Rubiyah Yusof have pursued the new developments of fuzzy logic and neural networks to present a series volume on neuro-control methods. As they demonstrate in the opening pages of their book, there is an explosion of interest in this field. Publication and patent activity in these areas are ever growing according to international is timely. databases and hence, this volume The presentation of the material follows a complementary pattern. Reviews of existing control techniques are given along side an exposition of the theoretical constructions of fuzzy logic controllers, and controllers based on neural networks. This is an extremely useful methodology which yields rewards in the applications chapters. The series of applications includes one very thorough experimental sequence for the control of a hot-water bath.

Intelligent Control in Drying Alex Martynenko, Andreas Bück. 2018-09-03 Despite the available general literature in intelligent control, there is a definite lack of knowledge and know-how in practical applications of intelligent control in drying. This book fills that gap. Intelligent Control in Drying serves as an innovative and practical guide for researchers and professionals in the field of drying technologies, providing an overview of control principles and systems used in drying operations, from classical to model-based to adaptive and optimal control. At the same time, it lays out approaches to synthesis of control systems, based on the objectives and control strategies, reflecting complexity of drying process and material under drying. This essential reference covers both fundamental and practical aspects of intelligent control, sensor fusion and dynamic optimization with respect to drying.

Nonlinear System Identification Oliver Nelles. 2013-03-09 Written from an engineering point of view, this book covers the most common and important approaches for the identification of nonlinear static and dynamic systems. The book also provides the reader with the necessary background on optimization techniques, making it fully self-contained. The new edition includes exercises.

Advances In Intelligent Control C J Harris. 1994-03-11 Advances in intelligent Control is a collection of essays covering the latest research in the field. Based on a special issue of The International Journal of Control, the book is arranged in two parts. Part one contains recent contributions of artificial neural networks to modelling and control. Part two concerns itself primarily with aspects of fuzzy logic in intelligent control, guidance and estimation, although some of the contributions either make direct equivalence relationships to neural networks or use hybrid methods where a neural network is used to develop the fuzzy rule base.

Adaptive Approximation Based Control Jay A. Farrell, Marios M. Polycarpou. 2006-04-14 A highly accessible and unified approach to the design and analysis of intelligent control systems Adaptive Approximation Based Control is a tool every control designer should have in his or her control toolbox. Mixing approximation theory, parameter estimation, and feedback control, this book presents a unified approach designed to enable readers to apply adaptive approximation based control to existing systems, and, more importantly, to gain enough intuition and understanding to manipulate and combine it with other control tools for applications that have not been encountered before. The authors provide readers with a thought-provoking framework for rigorously considering such questions as: * What properties should the function approximator have? * Are certain families of approximators superior to others? * Can the stability and the convergence of the approximator parameters be guaranteed? * Can control systems be designed to be robust in the face of noise, disturbances, and unmodeled effects? * Can this approach handle significant changes in the dynamics due to such disruptions as system failure? * What types of nonlinear dynamic systems are amenable to this approach? * What are the limitations of adaptive approximation based control? Combining theoretical formulation and design techniques with extensive use of simulation examples, this book is a stimulating text for researchers and

graduate students and a valuable resource for practicing engineers.

Neuro-control Systems Madan M. Gupta, Dandina H. Rao, IEEE Neural Networks Council. 1994

European Control Conference 1993 .1993-06-28 Proceedings of the European Control Conference 1993, Groningen, Netherlands, June 28 - July 1, 1993

Neural Systems for Control Omid Omidvar, David L. Elliott. 1997-02-24 Control problems offer an industrially important application and a guide to understanding control systems for those working in Neural Networks. Neural Systems for Control represents the most up-to-date developments in the rapidly growing application area of neural networks and focuses on research in natural and artificial neural systems directly applicable to control or making use of modern control theory. The book covers such important new developments in control systems such as intelligent sensors in semiconductor wafer manufacturing; the relation between muscles and cerebral neurons in speech recognition; online compensation of reconfigurable control for spacecraft aircraft and other systems; applications to rolling mills, robotics and process control; the usage of past output data to identify nonlinear systems by neural networks; neural approximate optimal control; model-free nonlinear control; and neural control based on a regulation of physiological investigation/blood pressure control. All researchers and students dealing with control systems will find the fascinating Neural Systems for Control of immense interest and assistance. Focuses on research in natural and artificial neural systems directly applicable to control or making use of modern control theory Represents the most up-to-date developments in this rapidly growing application area of neural networks Takes a new and novel approach to system identification and synthesis

Neural Network Engineering in Dynamic Control Systems Kenneth J. Hunt, George R. Irwin, Kevin Warwick. 2012-12-06 The series Advances in Industrial Control aims to report and encourage technology transfer in control engineering. The rapid development of control technology impacts all areas of the control discipline. New theory, new controllers, actuators, sensors, new industrial processes, computer methods, new applications, new philosophies, ... , new challenges. Much of this development work resides in industrial reports, feasibility study papers and the reports of advanced collaborative projects. The series offers an opportunity for researchers to present an extended exposition of such new work in all aspects of industrial control for wider and rapid dissemination. Within the control community there has been much discussion of and interest in the new Emerging Technologies and Methods. Neural networks along with Fuzzy Logic and Expert Systems is an emerging methodology which has the potential to contribute to the development of intelligent control technologies. This volume of some thirteen chapters edited by Kenneth Hunt, George Irwin and Kevin Warwick makes a useful contribution to the literature of neural network methods and applications. The chapters are arranged systematically progressing from theoretical foundations, through the training aspects of neural nets and concluding with four chapters of applications. The applications include problems as diverse as oven temperature control, and energy/load forecasting routines. We hope this interesting but balanced mix of material appeals to a wide range of readers from the theoretician to the industrial applications engineer.

Intelligent Control Zi-Xing Cai. 1997 Introduction; Methodology of knowledge representation; General inference principles; Hierarchical control systems; Expert control systems; Fuzzy control systems; Neurocontrol systems; Learning control systems; Intelligent control systems in application; Prospectives of intelligent control; References; Bibliography; Subject index.

Knowledge-Based Systems, Four-Volume Set Cornelius T. Leondes. 2000-07-11 The design of knowledge systems is finding myriad applications from corporate databases to general decision support in areas as diverse as engineering, manufacturing and other industrial processes, medicine, business, and economics. In engineering, for example, knowledge bases can be utilized for reliable electric power system operation. In medicine they support complex diagnoses, while in business they inform the process of strategic planning. Programmed securities trading and the defeat of chess champion Kasparov by IBM's Big Blue are two familiar examples of dedicated knowledge bases in combination with an expert system for decision-making. With volumes covering Implementation, Optimization, Computer Techniques, and Systems and Applications, this comprehensive set constitutes a unique reference source for students, practitioners, and researchers in computer science, engineering, and the broad range of applications areas for knowledge-based systems.

Modern Heuristic Optimization Techniques Kwang Y. Lee, Mohamed A. El-Sharkawi. 2008-01-28 This book explores how developing solutions with heuristic tools offers two major advantages: shortened development time and more robust systems. It begins with an overview of modern heuristic techniques and goes on to cover specific applications of heuristic approaches to power system problems, such as security assessment, optimal power flow, power system scheduling and operational planning, power generation expansion planning, reactive power planning, transmission and distribution planning, network reconfiguration, power system control, and hybrid systems of heuristic methods.

Balanced Control of Flexible Structures Wodek Gawronski. 2006-04-10 Methods of structural control and dynamics are introduced in this book. These include reduction of large structural models by balanced truncation, placement of actuators and sensors for dynamic testing and control, structural identification of the minimum-order balanced representation, balanced dissipative controller design, balanced LQG and H(controller designs with the closed-form relationships between controller parameters and system performance, and controller reduction methods that preserve the closed-loop performance. The book explores the unique properties of flexible structures to obtain efficient methods of dynamic analysis and controller design. The presented methods of structural dynamics, identification, sensor/actuator placement, and passive, LQG and H(controller design have been checked both with simulations and industrial implementations.

Neuro-Fuzzy Control of Industrial Systems with Actuator Nonlinearities Frank L. Lewis, Javier Campos, Rastko Selmic. 2002-01-01 Brings neural networks and fuzzy logic together with dynamical control systems. Each chapter presents powerful control approaches for the design of intelligent controllers to compensate for actuator nonlinearities.

Computational Science And Its Applications - Iccsa 2005 Osvaldo Gervasi. 2005-04-27 The four-volume set LNCS 3480-3483 constitutes the refereed proceedings of the International Conference on Computational Science and Its Applications, ICCSA 2005, held in Singapore in May 2005. The four volumes present a total of 540 papers selected from around 2700 submissions. The papers span the whole range of computational science, comprising advanced applications in virtually all sciences making use of computational techniques as well as foundations, techniques, and methodologies from computer science and mathematics, such as high performance computing and communication, networking, optimization, information systems and technologies, scientific visualization, graphics, image processing, data analysis, simulation and modelling, software systems, algorithms, security, multimedia etc.

Applications and Science of Artificial Neural Networks .1996

Proceedings, IEEE International Symposium on Intelligent Control .1996

High-Level Feedback Control with Neural Networks Young Ho Kim, Frank L. Lewis. 1998 Complex industrial or robotic systems with uncertainty and disturbances are difficult to control. As system uncertainty or performance requirements increase, it becomes necessary to augment traditional feedback controllers with additional feedback loops that effectively add intelligence to the system. Some theories of artificial intelligence (AI) are now showing how complex machine systems should mimic human cognitive and biological processes to improve their capabilities for dealing with uncertainty. This book bridges the gap between feedback control and AI. It provides design techniques for high-level neural-network feedback-control topologies that contain servo-level feedback-control loops as well as AI decision and training at the higher levels. Several advanced feedback topologies containing neural networks are presented, including dynamic output feedback, reinforcement learning and optimal design, as well as a fuzzy-logic reinforcement controller. The control topologies are intuitive, yet are derived using sound mathematical principles where proofs of stability are given so that closed-loop performance can be relied upon in using these control systems. Computer-simulation

examples are given to illustrate the performance.

Artificial Intelligence in Industrial Decision Making, Control and Automation S.G. Tzafestas,H. B. Verbruggen.2012-12-06 This book is concerned with Artificial Intelligence (AI) concepts and techniques as applied to industrial decision making, control and automation problems. The field of AI has been expanded enormously during the last years due to that solid theoretical and application results have accumulated. During the first stage of AI development most workers in the field were content with illustrations showing ideas at work on simple problems. Later, as the field matured, emphasis was turned to demonstrations that showed the capability of AI techniques to handle problems of practical value. Now, we arrived at the stage where researchers and practitioners are actually building AI systems that face real-world and industrial problems. This volume provides a set of twenty four well-selected contributions that deal with the application of AI to such real-life and industrial problems. These contributions are grouped and presented in five parts as follows: Part 1: General Issues Part 2: Intelligent Systems Part 3: Neural Networks in Modelling, Control and Scheduling Part 4: System Diagnostics Part 5: Industrial Robotic, Manufacturing and Organizational Systems Part 1 involves four chapters providing background material and dealing with general issues such as the conceptual integration of qualitative and quantitative models, the treatment of timing problems at system integration, and the investigation of correct reasoning in interactive man-robot systems.

Neurocontrol H. Tolle,E. Ersü.2014-10-08

Artificial Intelligence in Real-Time Control 1992 M.G. Rodd,H.B. Verbruggen.2014-06-28 The symposium had two main aims, to investigate the state-of-the-art in the application of artificial intelligence techniques in real-time control, and to bring together control system specialists, artificial intelligence specialists and end-users. Many professional engineers working in industry feel that the gap between theory and practice in applying control and systems theory is widening, despite efforts to develop control algorithms. Papers presented at the meeting ranged from the theoretical aspects to the practical applications of artificial intelligence in real-time control. Themes were: the methodology of artificial intelligence techniques in control engineering; the application of artificial intelligence techniques in different areas of control; and hardware and software requirements. This symposium showed that there exist alternative possibilities for control based on artificial intelligence techniques.

Intelligent Control Systems Using Computational Intelligence Techniques A.E. Ruano.2005-07-18 Intelligent Control techniques are becoming important tools in both academia and industry. Methodologies developed in the field of soft-computing, such as neural networks, fuzzy systems and evolutionary computation, can lead to accommodation of more complex processes, improved performance and considerable time savings and cost reductions. Intelligent Control Systems using Computational Intelligence Techniques details the application of these tools to the field of control systems. Each chapter gives an overview of current approaches in the topic covered, with a set of the most important references in the field, and then details the author's approach, examining both the theory and practical applications.

European Control Conference 1995 .1995-09-05 Proceedings of the European Control Conference 1995, Rome, Italy 5-8 September 1995

System Modelling and Optimization Jacques Henry,Jean-Pierre Yvon.2006-04-11 This conference, organized jointly by UTC and INRIA, is the biennial general conference of the IFIP Technical Committee 7 (System Modelling and Optimization), and reflects the activity of its members and working groups. These proceedings contain a collection of papers (82 from the more than 400 submitted) as well as the plenary lectures presented at the conference.

Neuronal Network Research Horizons Martin L. Weiss.2007 In neuroscience, a neural network is a bit of conceptual juggernaut: the conceptual transition from neuroanatomy, a rigorously descriptive discipline of observed structure, to the designation of the parameters delimiting a 'network' can be problematic. In outline a neural network describes a population of physically interconnected neurons or a group of disparate neurons whose inputs or signalling targets define a recognisable circuit. Communication between neurons often involves an electrochemical process. The interface through which they interact with surrounding neurons usually consists of several dendrites (input connections), which are connected via synapses to other neurons, and one axon (output connection). If the sum of the input signals surpasses a certain threshold, the neuron sends an action potential (AP) at the axon hillock and transmits this electrical signal along the axon. This important book presents the latest research in this field.

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Neurocontrol Learning Control Systems Inspired By Introduction

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